

CALIBRATED CLAMPING DEVICE

Main Technological Area —► Mechanics

Keyword —► Calibrated Clamping | joint | assembly | spring | mounting thickness

Clamping device capable of clamping together two or more components by applying a precise and repetitive clamping force, thus avoiding the occurrence of unwanted deformation or tension on the coupled components.

**TECHNICAL FEATURES**

The operating principle of the device is based on the elastic behavior of a compression spring, i.e. on the ability to compress the spring against the coupled parts of a known quantity δx to transmit on them a force F of known value ($F = K \times \delta x$).

By calibrating the spring crushing on a graduated scale, it is therefore possible to apply, with rapidity, repeatability and precision, the exact value of the clamping force prescribed by the project.

INNOVATION/BENEFITS

- a) assembly without any undesired deformation or stress in the joint;
- b) exact and repetitive application of the clamping load in specific locations;
- c) wide 'range' of applicable forces;
- d) can also be used in areas with poor accessibility;
- e) possibility of identifying the forces required to recover deformation;
- f) adaptable to all thicknesses and diameters of hole.

AREAS OF USE

- a) Precise assembly of complex components;
- b) temporary couplings with punctual and calibrated clamping forces;
- c) systems for measuring the forces required to deform or move components.



PATENT INFORMATION

Priority Date – 2011/04/22

Priority Number - IT TO20110358

IPC Codes– B25B 05/06 | B25B 05/10 | B25B 31/00 | F16B 05/02 | F16B 19/10 | F16B 31/02 | G01L 01/04

Active Worldwide Extensions

EPO – EP2514565B1; Filing Date 2012/04/20 ; Grant Date 2014/07/02/

Italy - Germany – France – United Kingdom – Spain

USA US9168681; Filing Date 2012/04/19; Grant Date 2015/10/27

Leonardo internal code

LDO -A473

